

FIG. 1 is a schematic diagram of a device 100. The device 100 includes a substrate 10, a layer 12, a layer 14, a layer 16, and a layer 18. The substrate 10 is a thin, flexible layer. The layer 12 is a thin, flexible layer. The layer 14 is a thin, flexible layer. The layer 16 is a thin, flexible layer. The layer 18 is a thin, flexible layer.

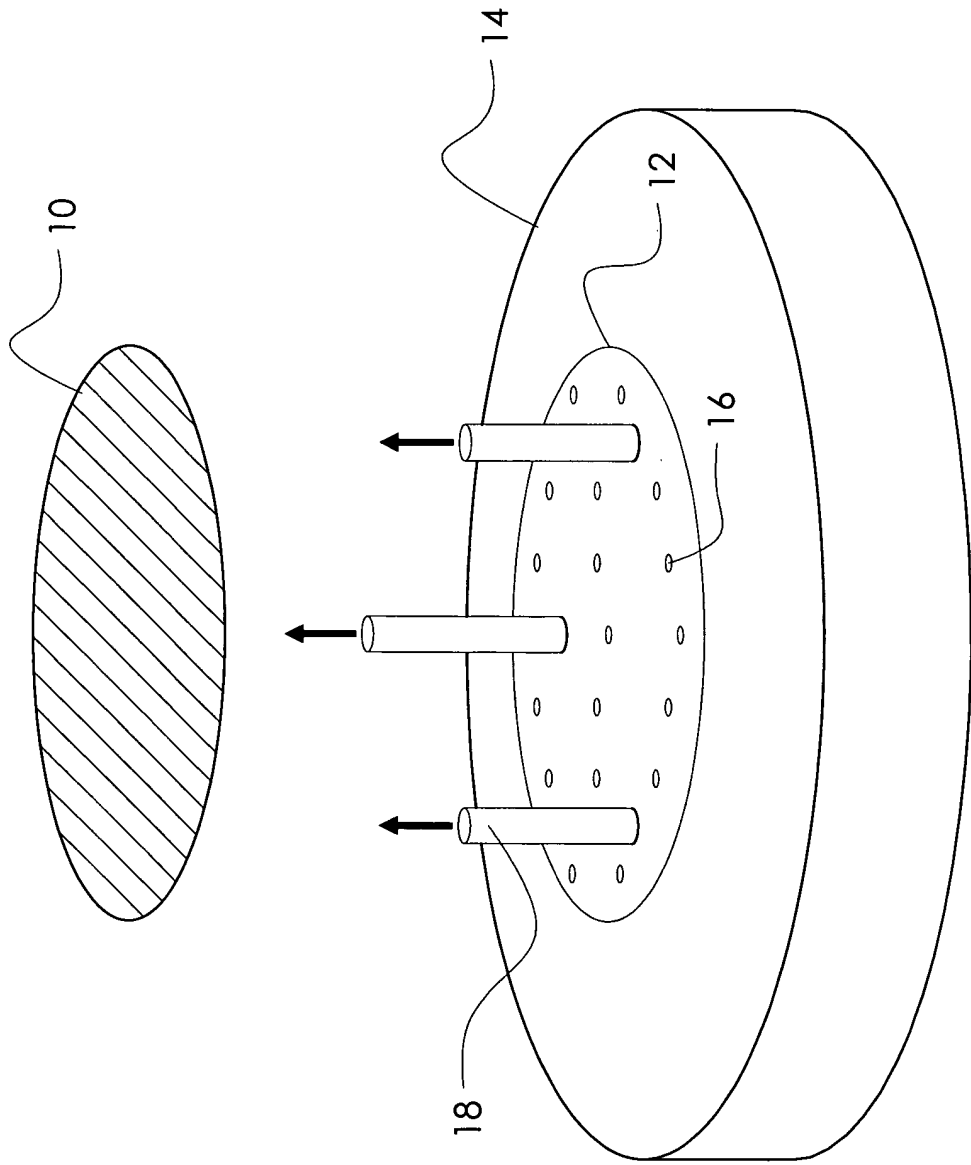


Fig. 1

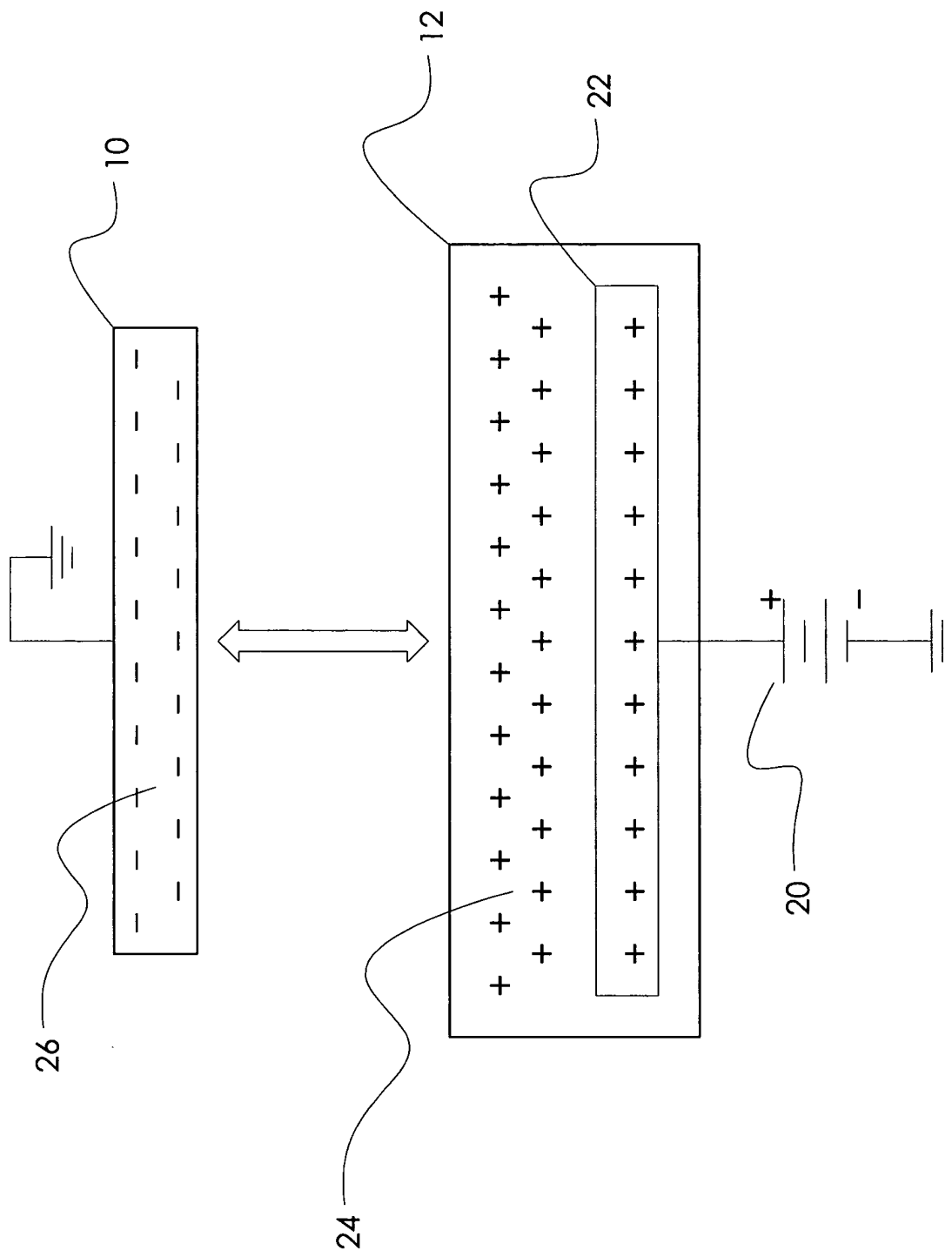


Fig. 2

FIG. 3 is a schematic diagram of a device 10, showing a top view of the device 10. The device 10 includes a substrate 12, a first conductive layer 30a, a second conductive layer 30b, a first insulating layer 32a, a second insulating layer 32b, a first gate electrode 34a, a second gate electrode 34b, a first gate insulating layer 36a, and a second gate insulating layer 36b. The first gate electrode 34a is connected to a first terminal 30a, and the second gate electrode 34b is connected to a second terminal 30b. The first gate insulating layer 36a is connected to the first terminal 30a, and the second gate insulating layer 36b is connected to the second terminal 30b. The first insulating layer 32a is connected to the first terminal 30a, and the second insulating layer 32b is connected to the second terminal 30b. The first conductive layer 30a is connected to the first terminal 30a, and the second conductive layer 30b is connected to the second terminal 30b. The substrate 12 is connected to the first terminal 30a, and the substrate 12 is connected to the second terminal 30b.

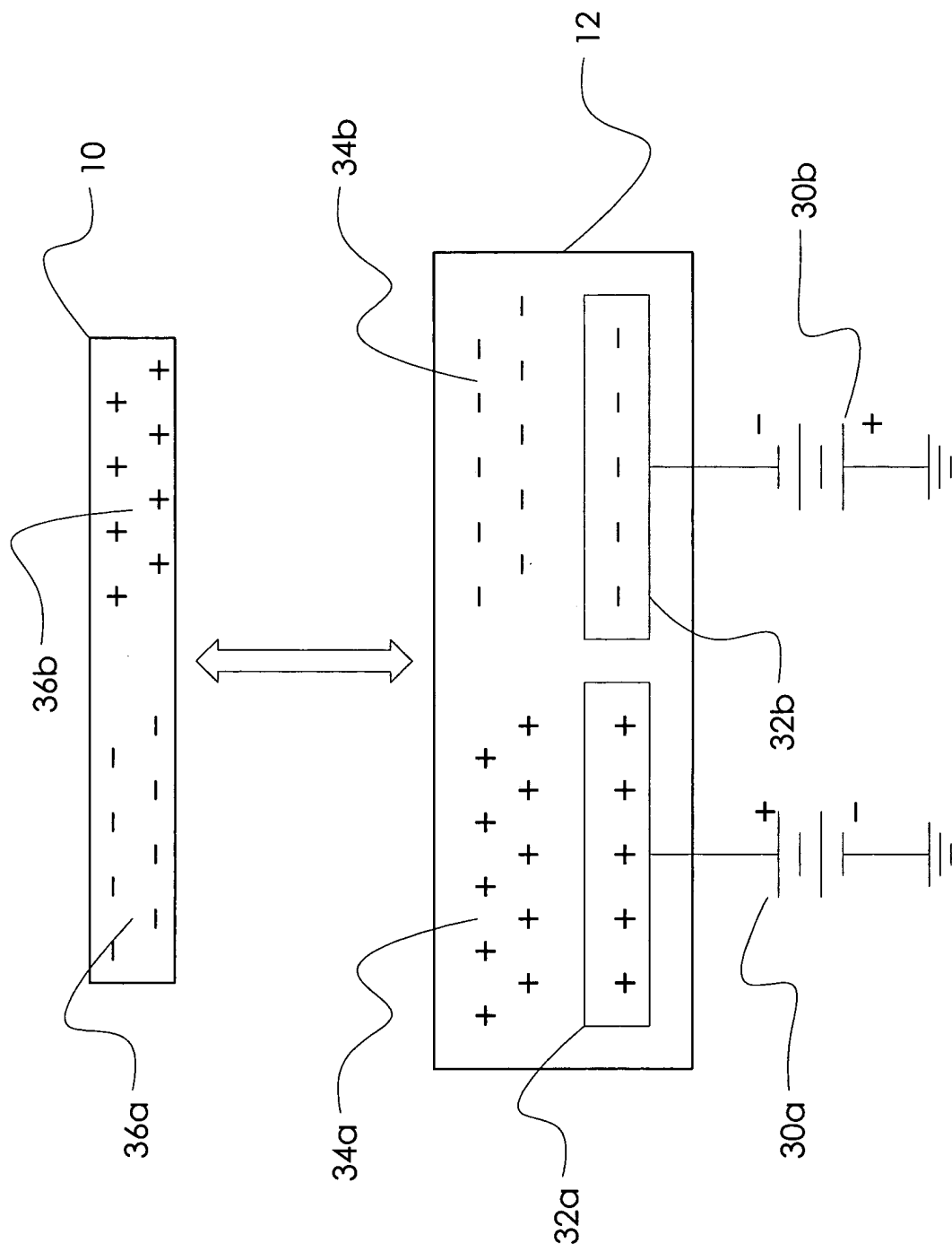


Fig. 3

FIG. 4 is a block diagram of a control system for a vehicle. The system includes a control system 46, a vehicle 10, and a driver 12. The control system 46 is connected to the vehicle 10 via a communication link 48. The driver 12 is connected to the vehicle 10 via a communication link 44. The vehicle 10 includes a sensor 18a and a sensor 18b. The sensor 18a is connected to the control system 46 via a communication link 40a. The sensor 18b is connected to the control system 46 via a communication link 40b. The control system 46 is also connected to a power source 80 via a communication link 82. The power source 80 is connected to the vehicle 10 via a communication link 82.

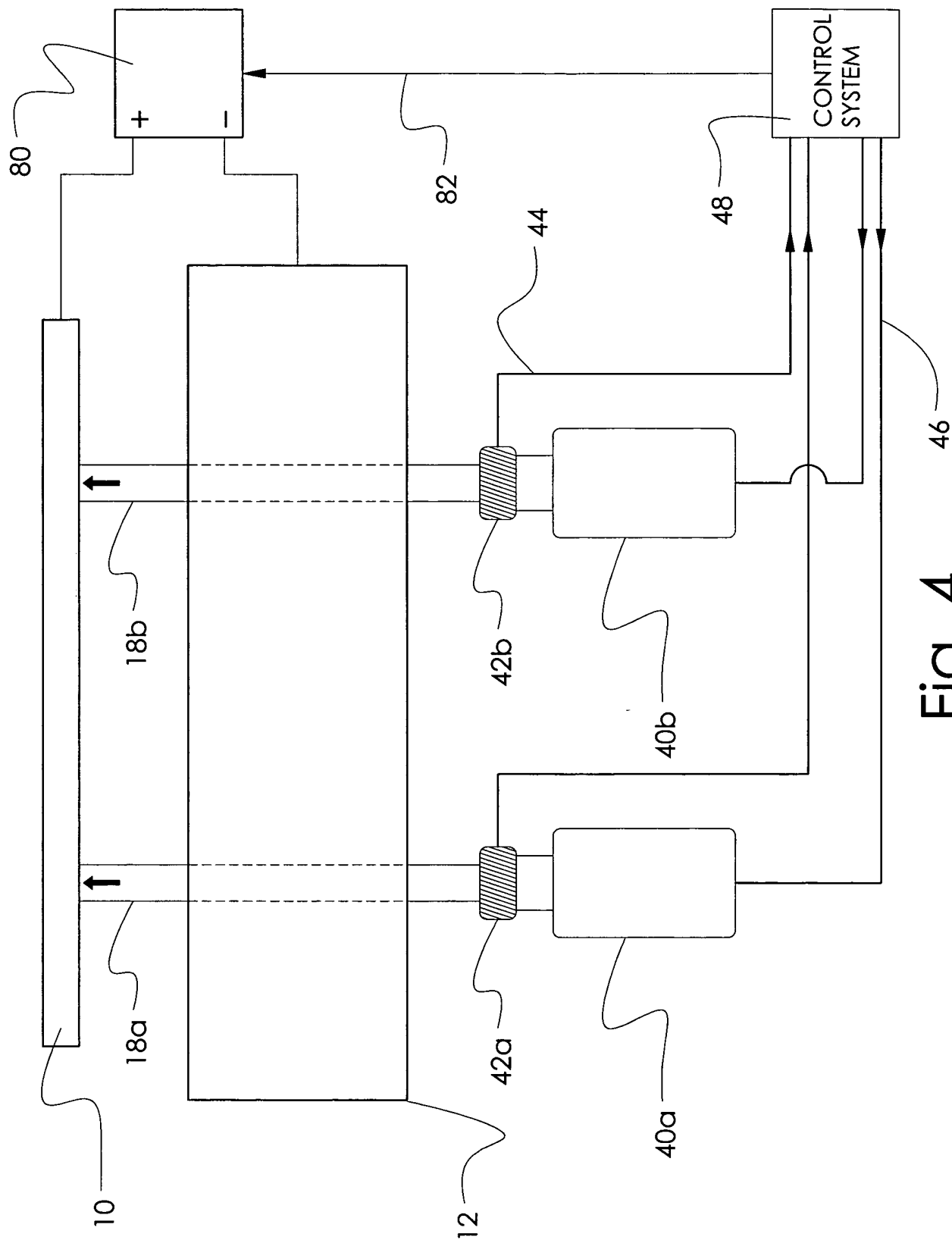


Fig. 4

FIG. 5 is a block diagram of a control system for a vehicle. The system includes a control system 46, a first actuator 40a, a second actuator 40b, a first sensor 18a, a second sensor 18b, a first output 80, and a second output 82. The control system 46 is connected to the first actuator 40a and the second actuator 40b. The first actuator 40a is connected to the first sensor 18a. The second actuator 40b is connected to the second sensor 18b. The first sensor 18a is connected to the first output 80. The second sensor 18b is connected to the second output 82. The control system 46 is also connected to the first output 80 and the second output 82.

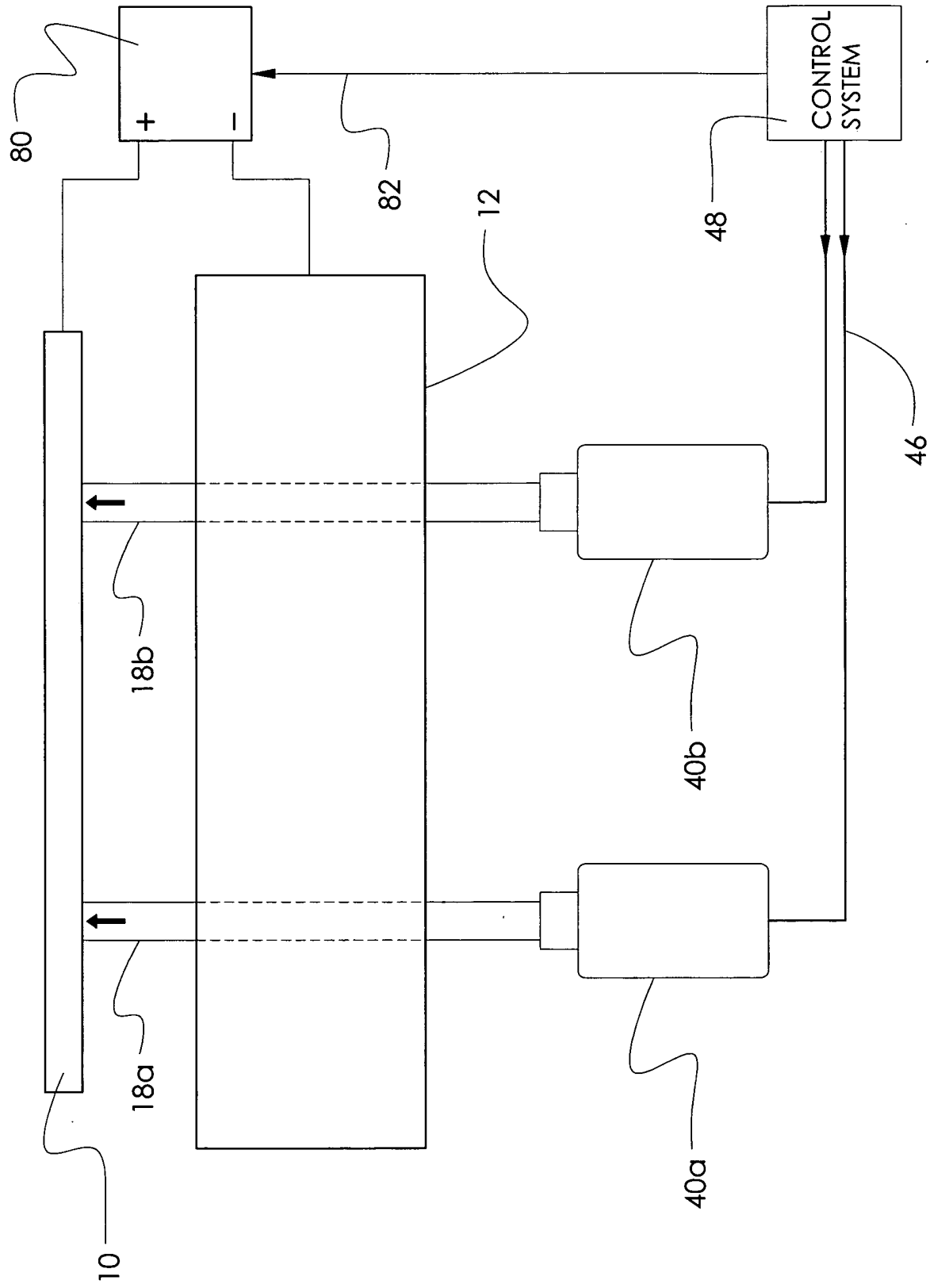


Fig. 5

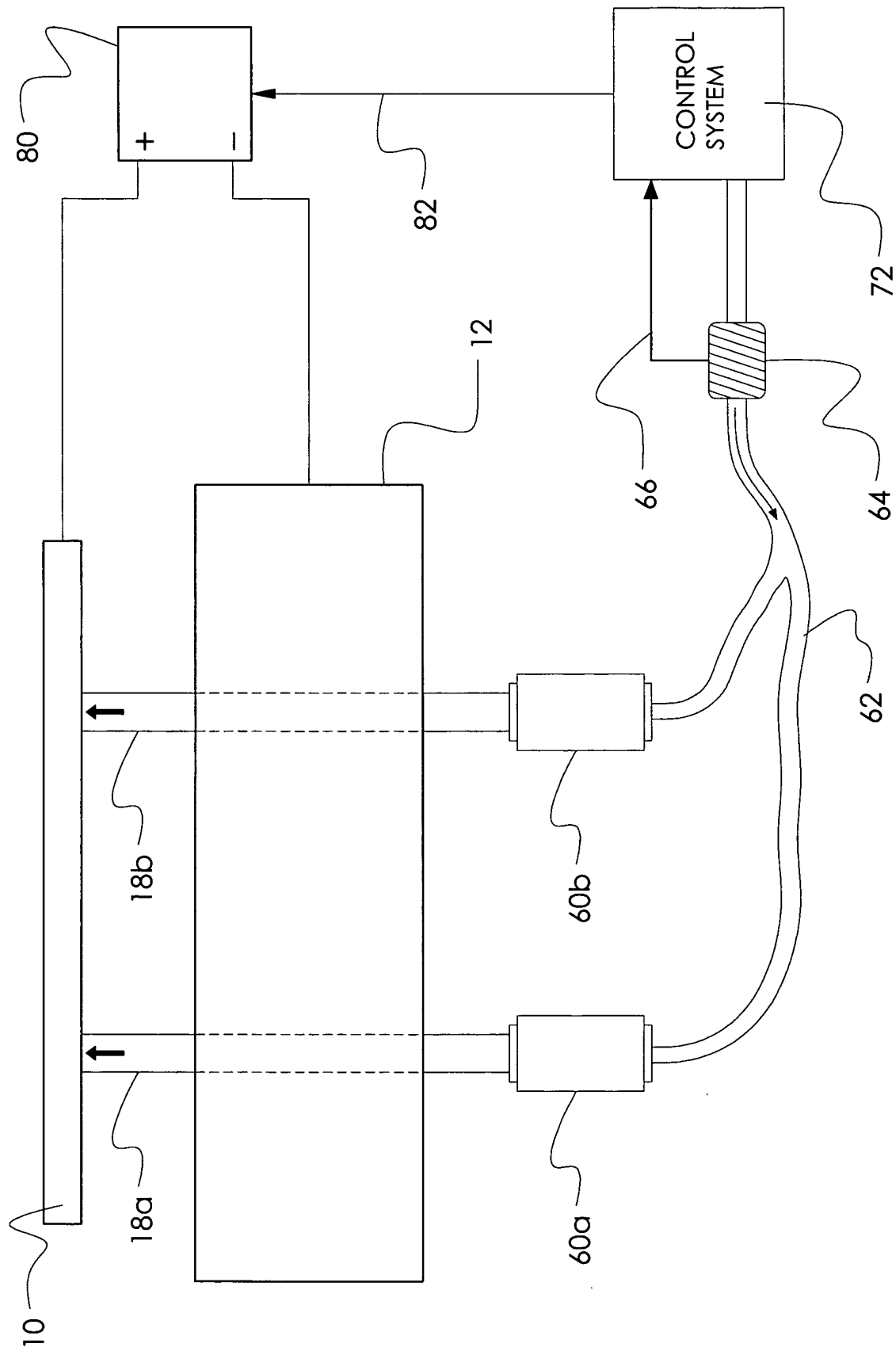


Fig. 6

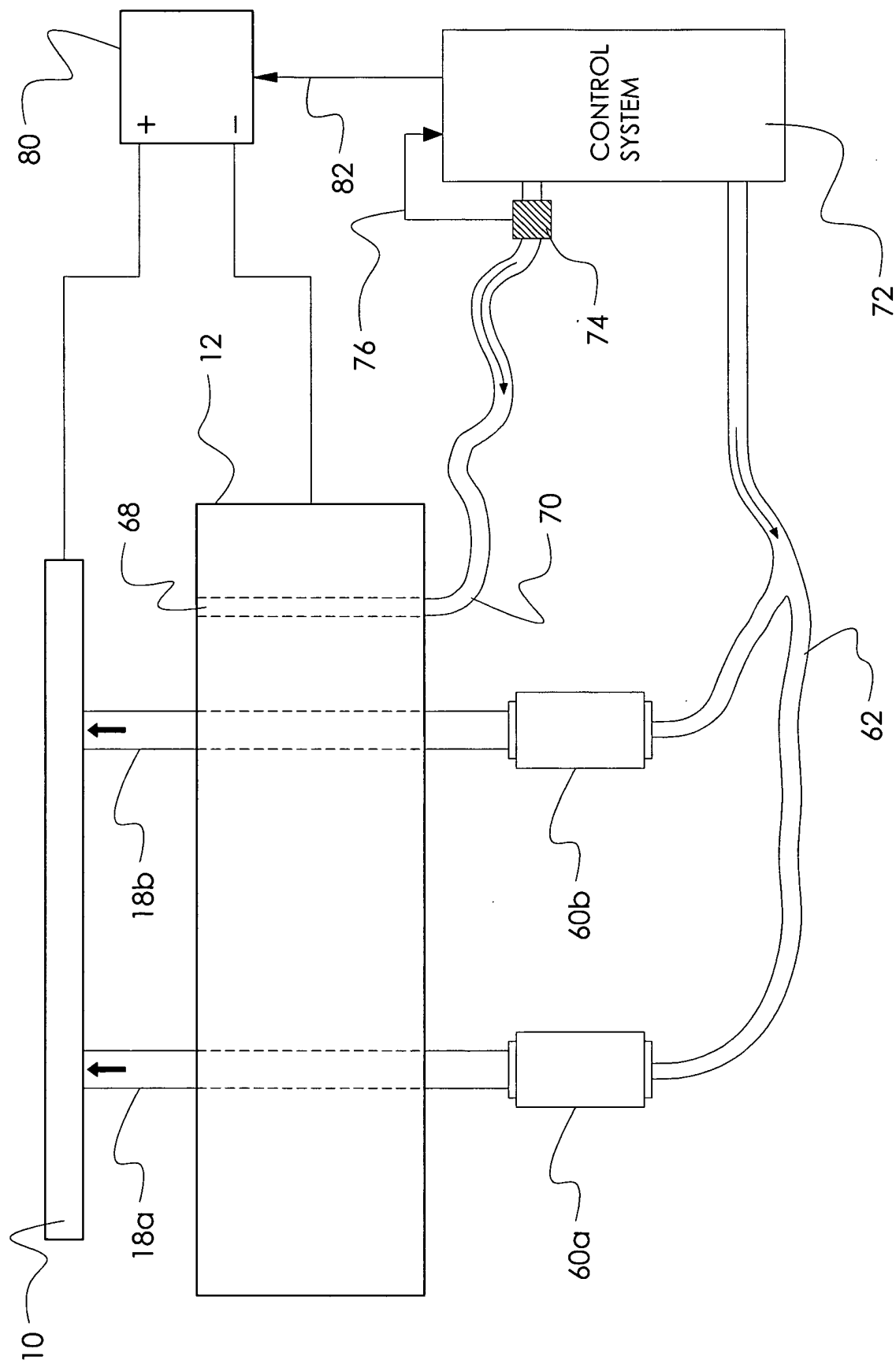


Fig. 7